

Course Description

This course provides a thorough introduction to the Vivado® High-Level Synthesis (HLS) tool. It covers synthesis strategies, features, improving throughput, area, interface creation, latency, testbench coding, and coding tips. Use the Vivado HLS tool to optimize code for high-speed performance in an embedded environment and download for in-circuit validation.

Level – DSP 3

Course Duration – 2 days

Price – \$1600 or 16 Xilinx Training Credits

Course Part Number – DSP-HLS-ILT

Who Should Attend? – Software and hardware engineers looking to utilize high-level synthesis

Prerequisites

- C, C++, or System C knowledge
- High-level synthesis for software engineers OR high-level synthesis for hardware engineers

Recommend

- [Designing FPGAs Using the Vivado Design Suite 1](#)

Follow-up training

- [Embedded C/C++ SDSoC Development Environment and Methodology](#)

Software Tools

- Vivado System Edition 2017.3
- SDx™ development environment 2016.3
- MATLAB R2017a

Hardware

- Architecture: Zynq®-7000 All Programmable SoC and 7 series FPGAs*
- Demo board: Zynq-7000 All Programmable SoC ZC702 or Zed board and Kintex®-7 FPGA KC705 board*

* This course focuses on the Zynq-7000 All Programmable SoC and 7 series FPGA architectures. Check with [North Pole Engineering, Inc.](#) for the specifics of the in-class lab board or other customizations.

After completing this comprehensive training, you will have the necessary skills to:

- Enhance productivity using the Vivado HLS tool
- Describe the high-level synthesis flow
- Use the Vivado HLS tool for a first project
- Identify the importance of the testbench
- Use directives to improve performance and area and select RTL interfaces
- Identify common coding pitfalls as well as methods for improving code for RTL/hardware
- Perform system-level integration of IP generated by the Vivado HLS tool
- Describe how to use OpenCV functions in the Vivado HLS tool

Course Outline

Day 1

- Introduction to High-Level Synthesis {Lecture}
- Basics of the Vivado HLS Tool {Lecture, Demo, Lab}
- Design Exploration with Directives {Lecture}
- Vivado HLS Tool Command Line Interface {Lecture, Lab}
- Introduction to HLS UltraFast Design Methodology {Lecture}
- Introduction to I/O Interfaces {Lecture}
- Block-Level Protocols {Lecture, Lab}
- Port-Level Protocols {Lecture, Demo, Lab}
- Port-Level Protocols: AXI4 Interfaces {Lecture, Demo}

- Port-Level Protocols: Memory Interfaces {Lecture, Lab}
- Port-Level Protocols: Bus Protocol {Lecture}
- Pipeline for Performance: PIPELINE {Lecture, Demo, Lab}

Day 2

- Pipeline for Performance: DATAFLOW {Lecture, Lab}
- Optimizing Structures for Performance {Lecture, Demo, Lab}
- Data Pack and Data Dependencies {Lecture}
- Vivado HLS Tool Default Behavior - Latency {Lecture}
- Reduce Latency {Lecture}
- Improving Area {Lecture, Lab}
- Introduction to HLx Design Flow {Lecture, Demo, Lab}
- HLS vs. SDSoC Development Environment Flow {Lecture, Demo}
- Vivado HLS Tool: C Code {Lecture, Lab}
- Hardware Modeling {Lecture}
- OpenCV Libraries {Lecture}
- Pointers {Lecture}

Topic Descriptions

Day 1

- Introduction to High-Level Synthesis – Overview of the High-level Synthesis (HLS), Vivado HLS tool flow, and the verification advantage.
- Basics of the Vivado HLS Tool – Explore the basics of high-level synthesis and the Vivado HLS tool.
- Design Exploration with Directives – Explore different optimization techniques that can improve the design performance.
- Vivado HLS Tool Command Line Interface – Describes the Vivado HLS tool flow in command prompt mode.
- Introduction to HLS UltraFast Design Methodology – Introduces the methodology guidelines covered in this course and the HLS UltraFast Design Methodology steps.
- Introduction to I/O Interfaces – Explains interfaces such as block-level and port-level protocols abstracted by the Vivado HLS tool from the C design.
- Block-Level Protocols – Explains the different types of block-level protocols abstracted by the Vivado HLS tool.
- Port-Level Protocols – Describes the port-level interface protocols abstracted by the Vivado HLS tool from the C design.
- Port-Level Protocols: AXI4 Interfaces – Explains the different AXI interfaces (such as AXI4-Master, AXI4-Lite (Slave) and AXI4-Stream) supported by the Vivado HLS tool.
- Port-Level Protocols: Memory Interfaces – Describes the Memory Interface port-level protocols (such as BRAM, FIFO) abstracted by the Vivado HLS tool from the C design.
- Port-Level Protocols: Bus Protocol – Explains the bus protocol supported by the Vivado HLS tool.
- Pipeline for Performance: PIPELINE – Describes the PIPELINE directive for improving the throughput of a design.

Day 2

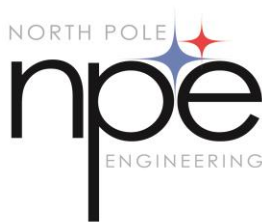
- Pipeline for Performance: DATAFLOW – Describes the DATAFLOW directive for improving the throughput of a design by pipelining the functions to executes as soon as possible.
- Optimizing Structures for Performance – Learn the performance limitations caused by arrays in your design. You will also learn some optimization techniques to handle arrays for improving performance.
- Data Pack and Data Dependencies – Learn how to use DATA_PACK and DEPENDENCE directives to overcome the limitations caused by structures and loops in the design.

- Vivado HLS Tool Default Behavior: Latency – Describes the default behavior of the Vivado HLS tool on latency and throughput.
- Reduce Latency – Describes how to optimize the C design to improve latency.
- Improving Area – Describes different methods for improving resource utilization and explains how some of the directives have impact on the area utilization.
- Introduction to HLx Design Flow – Describes the traditional RTL flow versus the Vivado HLx design flow.
- HLS vs. SDSoC Development Environment Flow – Describes the HLS flow versus the SDSoC™ development environment flow.
- Vivado HLS Tool: C Code – Describes the Vivado HLS tool support for the C/C++ languages, as well as arbitrary precision data types.
- Hardware Modeling – Explains hardware modeling with streaming data types and shift register implementation using the `ap_shift_reg` class.
- OpenCV Libraries – Explains the OpenCV design flow and the Vivado HLS tool support.
- Pointers – Explains the use of pointers in the design and workarounds for some of the limitations.

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